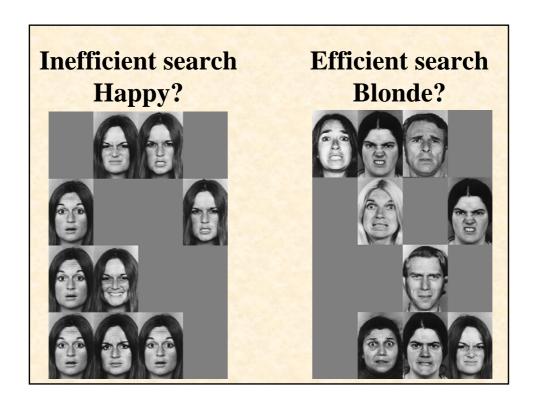
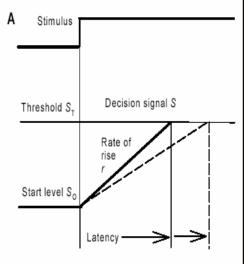
Self terminating, guided or accumulator models of visual search: Evidence from stimulus inversion

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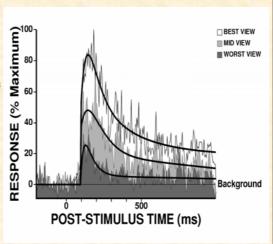
Accumulator models & visual search

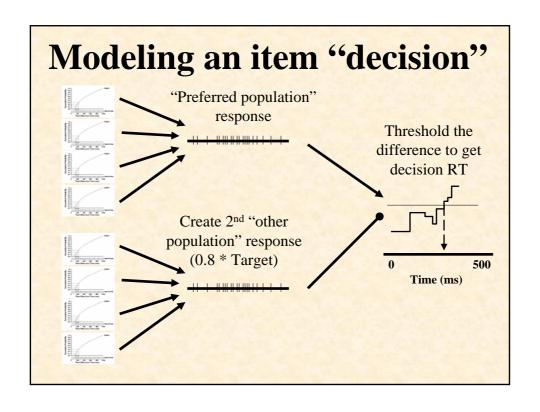
- Information acquisition hypothesis
 - E.g. Ratcliff 1978; McClelland 1979;
 Loftus 1983; Carpenter & Williams,
 1995; Gold & Shadlen, 2001



Accumulator models & visual search

- Data from macaque temporal lobe
 - Individual cell response profile (Oram & Perrett 1992)
 - Use numbers of neurones with "preferred" orientations to generate population responses (Wachsmuth et al 1994)



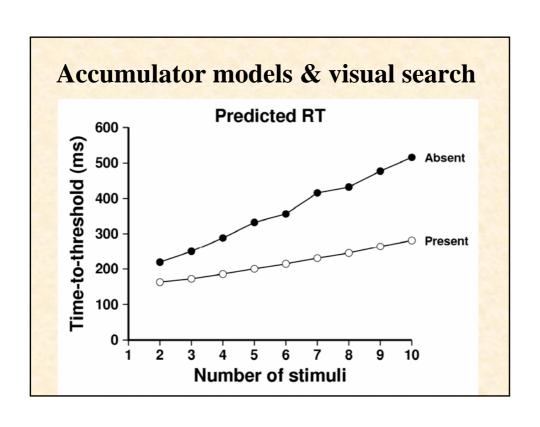


Accumulator models & visual search

- For each stimulus:
 - Preferred Population = maximally excited by stimulus
 - Other Population = 0.8 * Preferred Population
 - Target population has "attention" gain (e.g. Desimone & Duncan 1995; McAdams & Maunsell 1999; Reynolds & Desimone 2001)
- Model inhibitory interactions between stimulus representations:
 - Scale all responses by 1/sqrt(N) (Ward & McClelland 1989)

Accumulator models & visual search

- Compare "preferred population" responses with "other population" responses in parallel
 - Of interest is each "target population" versus "non-target population" comparison



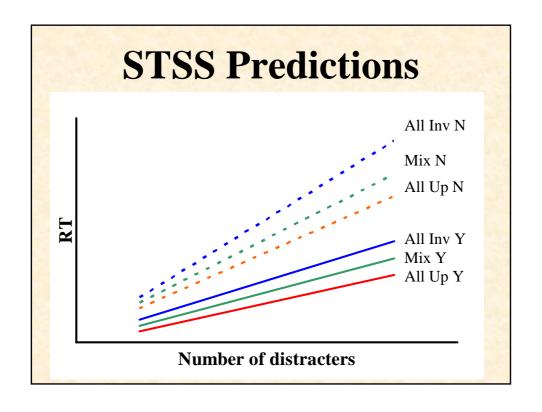
Visual search: Accumulator model

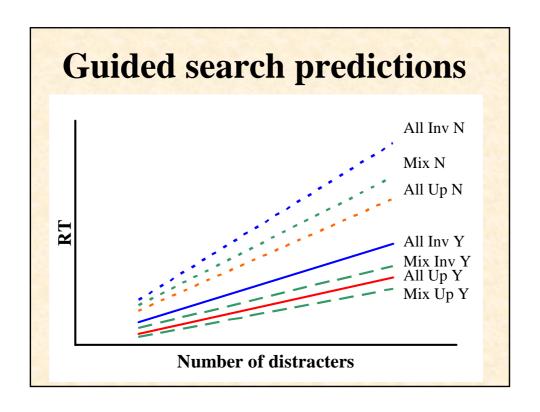
- RT related to difference in activity ("preferred" vs "distracter")
 - Attention "gain":
 - Target present difference > target absent
 - As set size increases:
 - Difference decreases
 - Inversion scales responses
 - Upright difference > Inverted difference
 - Effect of inversion on RT
 - Upright < Inverted
 - Scales with set size
 - Greater for target absent than target present

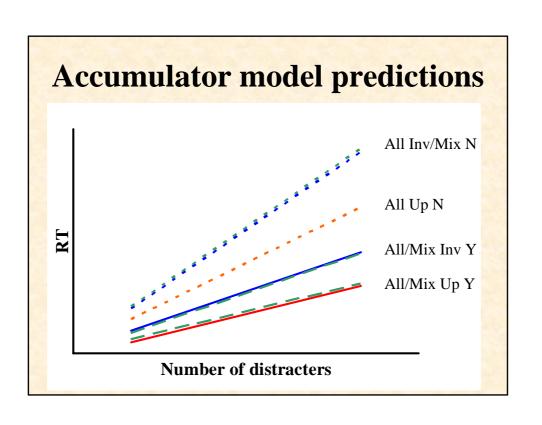
Accumulator model: Mixed inversion

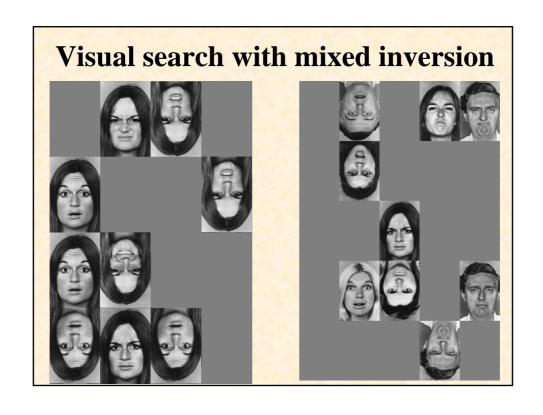
- RT(Y) determined by orientation of target
 - Target upright: Target upright vs distracter upright
 - Target inverted: Target inverted vs distracter inverted
 - All upright=Mix upright < All inverted=mix inverted
- RT(N) determined by presence of inverted item
 - With half upright half inverted:
 - Some non-target inverted vs distracter inverted (same as all inverted)
 - All upright < mix inversion=All inverted</p>

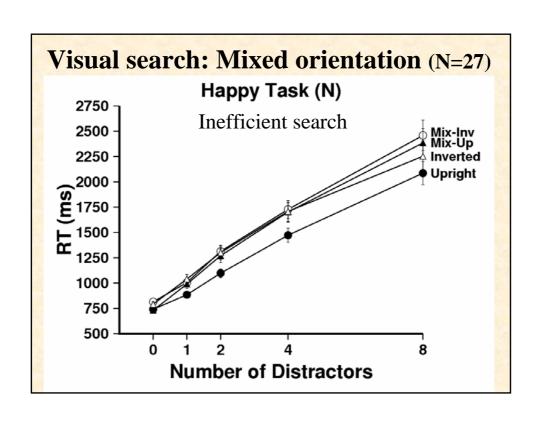
STSS and mixed Inversion Start • STSS (Treisman & Gelade 1980) - RT(Y) ½ items need rotating - RT(N) ½ items need rotating • Guided search (Wolfe et al. 1989) Νo Upright "more likely" than inverted? Is target? (t_{targ}, σ²_{targ}) • $RT(Y_{mix_up}) < RT(Y_{up})$ • $RT(Y_{mix_inv}) > RT(Y_{up})$ No Otherwise same pattern as STSS Last item? · But faster RT

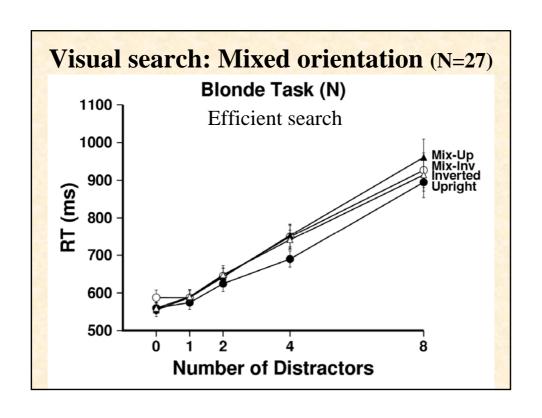


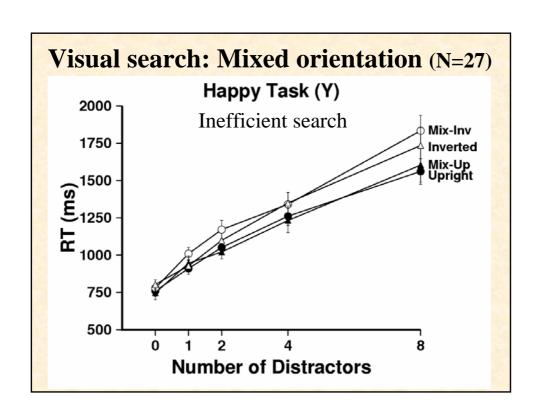


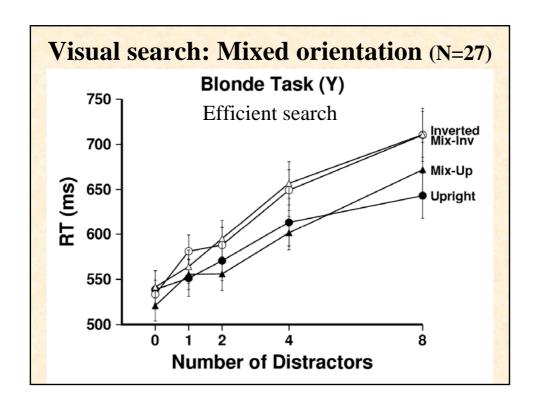












Summary of results

- Target present RT(Y)
 - determined by orientation of target
 - Mixed-upright target = all upright
 - Mixed-inverted target = all inverted
- Target absent RT(N)
 - -determined by an inverted item
 - Mixed = all inverted > all upright

Conclusions

- Can use "mixed" conditions to distinguish between models
- Data support accumulator model
 - over self-terminating & guided search models
 - also standard signal detection theory models (Palmer et al 2000; Verghese 2004)

Visual Search and VSTM

VSTM in visual search:

- Maybe not involved (Woodman et al. 2001)
- Executive processes (Han & Kim 2004)

OR Inhibitory interactions in visual system?

- Giving rise to attention gain: RT(Y) < RT(N)
- Increasing RT with increasing set size
- Executive processes "do the accumulation"
- Same model also can account for
 - Mental rotation, size normalisation (Perrett et al. 1998)
 - Dual task performance (Oram et al 2002; Oram under revision)